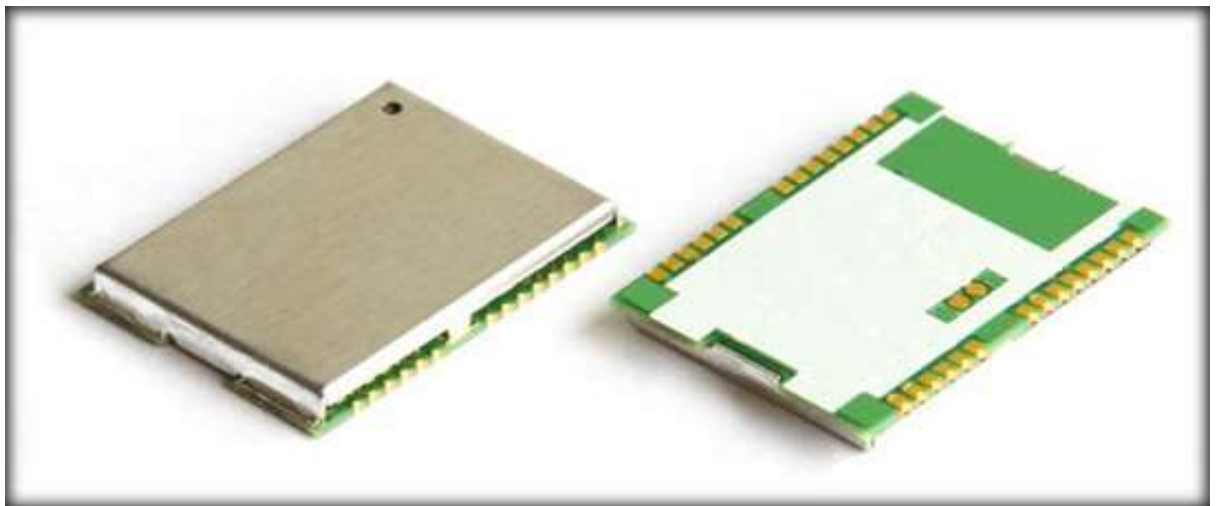


AscenKorea Inc.

# AKMU5LP GPS Module Data sheet

Revision: V0F



The AKMU5LP is a standard stand-alone GPS module with ultra-high sensitivity (-165dBm) in a popular form factor (22.4\*17\*2.2mm) that has super-efficient low power consumption and utilizes the new "Antenna Advisor" system.

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**Subtitle:** GPS Module

**Doc Type:** Datasheet

**Doc Id:** AS9905-DS000F

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V0A	2010-03-30	Dennis	First Release
V0B	2010-04-26	Dennis	Modify system block Diagram Modify VS_AA description Add application
V0C	2010-07-07	Dennis	Modify pin define(32pin to 28pin) Add pin8(NC/ANT_OK) description Add pin16(RF_IN) description Add antenna status detector table Add antenna status protocol table
V0D	2010-08-04	Dennis	Modify System Block Diagram Modify VBACKUP/USB_VCC pin description Add NMEA_Code (GLL) Modify PGACK description
V0E	2010-09-17	Dennis	Add Vibration Condition Tested Update Mechanical Dimension and Pad
V0F	2010-10-08	Dennis	Update Recommended PCB pad Layout Figure Update Pin Configuration Figure

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## 1. Functional Description

### 1.1 Overview

The AscenKorea AKMU5LP is a highly sensitive, low power consuming GPS module in a popular SMD form factor. It utilizes MediaTek GPS MT3329 solution that supports up to 66 channels of satellite searching with -165dBm sensitivity and 10Hz maximum update rate for precise GPS signal processing under low receptive, high velocity conditions.

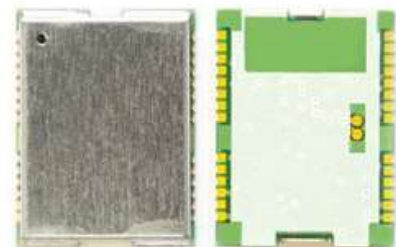
AKMU5LP comes with the addition of a power saving switching mode power supply (SMPS) that can help reduce the overall amount of GPS power consumption by over 30% when compared to the previous generation.

AKMU5LP also features a new antenna system called “Antenna Advisor” that helps with the detections and notifications of different antenna statuses, including active antenna connection, antenna open circuit and antenna shortage. It also features antenna shortage protection to safeguard the module from being damaged due to short circuiting at antenna I/O. “Antenna Advisor” is very easy to implement and requires only a single additional resistor.

The major advancement in power saving, plus hassle-free antenna I/O detection and protection, coupled with flexible GPS firmware customization, makes this GPS module in a popular SMD form factor an ideal solution for the next generation of mobile and embedded devices.

#### Suitable Application:

- ✓ AVL
- ✓ Personal Tracker
- ✓ Bike Computer
- ✓ Mobile Phone
- ✓ PND
- ✓ M2M
- ✓ Precise Timing Equipment



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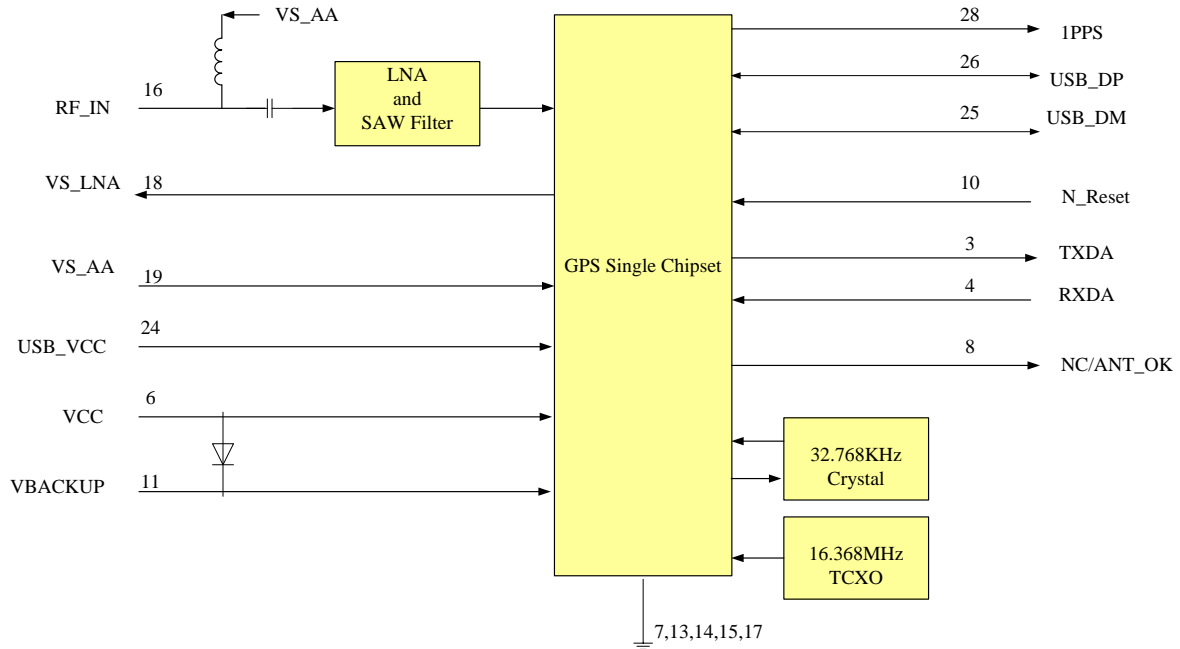
## 1.2 Highlights and Features

- ◆ Super Low Power Consumption with SMPS Power Saving Management:
  - Acquisition: 30mA Typical
  - Tracking: 24mA Typical
- ◆ “Antenna Advisor” - Active and Passive Antenna support with the following features and only a single additional resistor is required:
  - Active and Passive Antenna Detection & Notification
  - Open Circuit Detection & Notification
  - Short Circuit Protection & Notification
- ◆ Ultra-High Sensitivity: -165dBm<sup>1</sup>
- ◆ L1 Frequency, C/A code, 66-Channels Satellite Searching
- ◆ High Update Rate: up to 10Hz
- ◆ DGPS (WAAS/EGNOS/MSAS/GAGAN) Support
- ◆ AGPS Support for Fast TTFF
- ◆ Magnetic Variation Support (Configurable by Customized Firmware)
- ◆ 1-PPS Support for Timing Applications
- ◆ Multi-Path Detection and Compensation
- ◆ E-GSM-900 Band Rejection
- ◆ USB Interface support (Desktop Windows and Linux Platform<sup>2</sup>)
- ◆ Dimension: 22.4mm x 17mm x 2.2 mm
- ◆ E911, RoHS, REACH compliant

<sup>1</sup> Reference to GPS chipset specification

<sup>2</sup> To obtain Linux driver, please contact your AscenKorea GPS module dealer

## 1.3 System Block Diagram



## 1.4 Antenna Advisor

“Antenna Advisor” is a brand new antenna system available exclusively for Gmm-u5LP. It is designed to detect and notify antenna status using both hardware (through pin voltage level output) and software (through proprietary protocol).

Antenna Advisor can detect and notify the following:

- Active Antenna Connected
- Active Antenna Shortage
- Active Antenna Open (Not Connected), or Passive Antenna Connected (Antenna Advisor cannot differentiate these two)

In addition, Antenna Advisor can protect the module against shortage from external antenna by limiting the current drawn to a safe level. This is automatically activated whenever the system detects a load larger than 30mA at RF\_IN pin.

To implement Antenna Advisor, please go through the Pin requirements (Hardware) on **Chapter 2.5** and **Chapter 2.9**, software protocol readout on **Chapter 3.2**, and most importantly, the antenna reference circuit design on **Chapter 4**.

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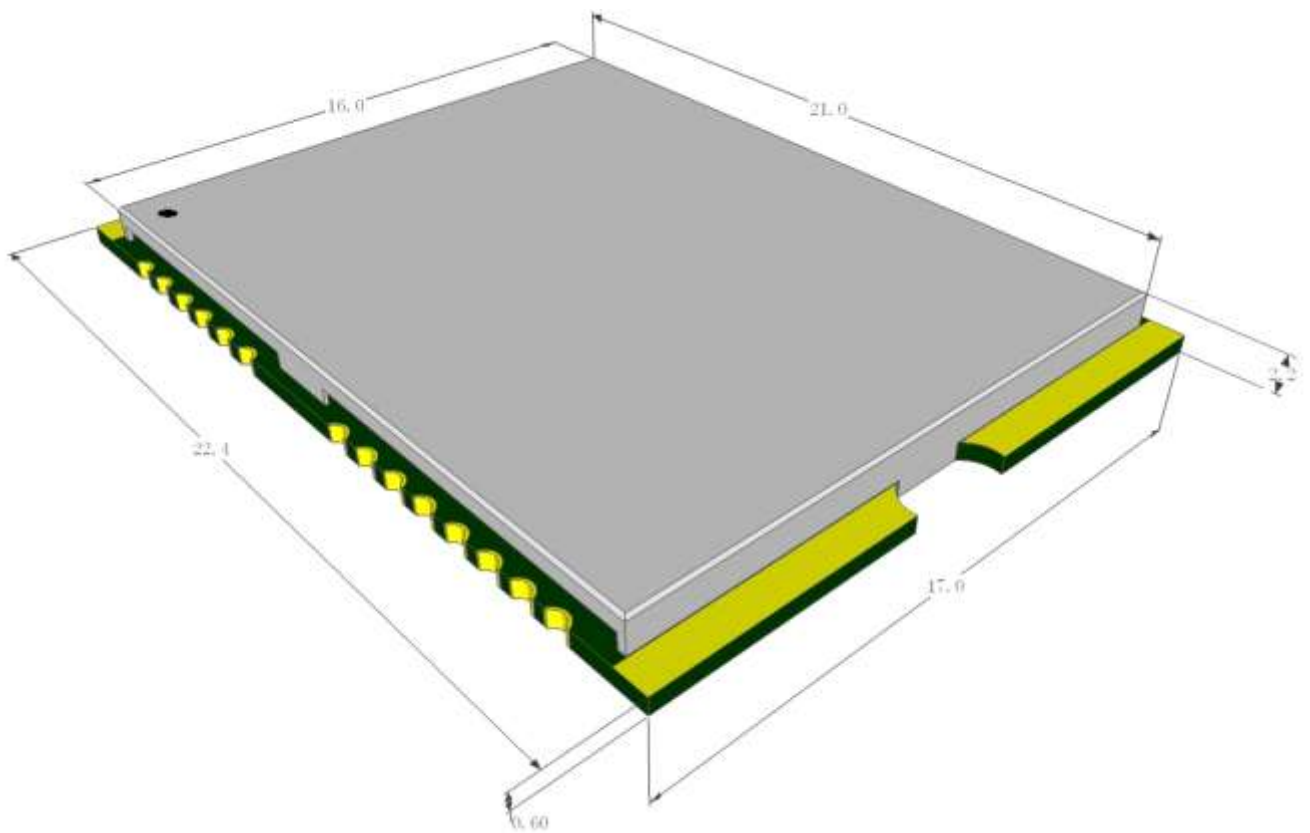




## 2. Specifications

### 2.1 Mechanical Dimension

(Unit: mm, Tolerance: 0.2 mm)



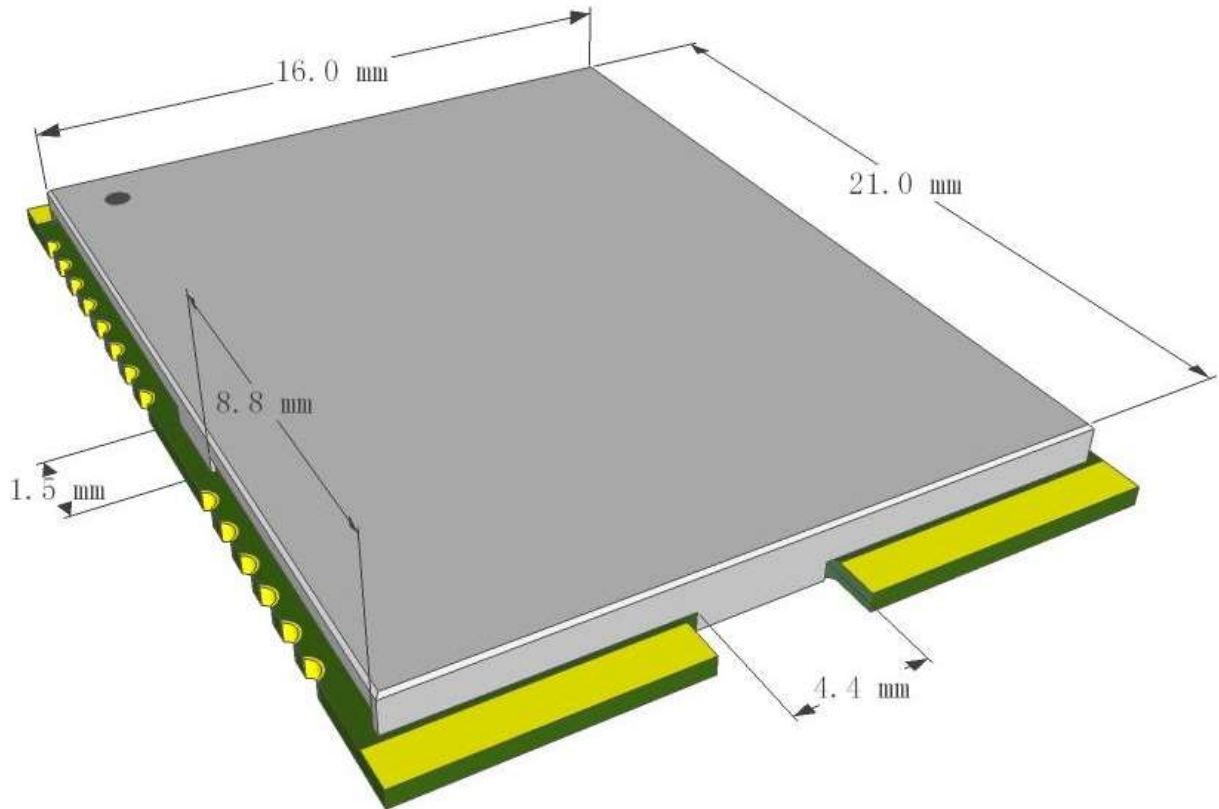
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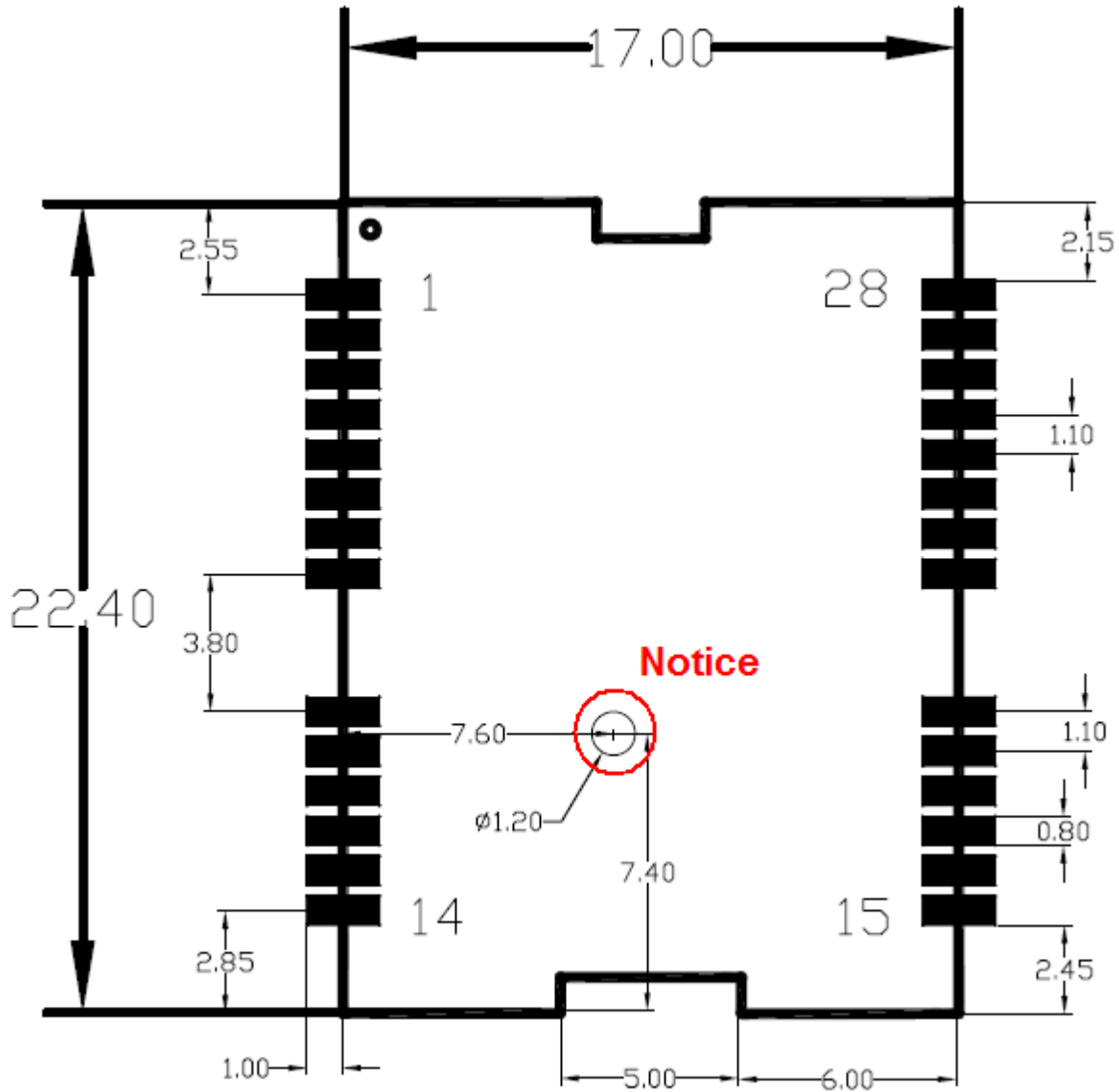
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## 2.2 Recommended PCB pad Layout

(Unit: mm, Tolerance: 0.1mm)



**Notice:**

To avoid contact with this 1mm diameter pin, please place one hole (diameter = > 3.0mm) under the module on the PCB pad for Gmm-u5LP. If the hole cannot be placed on the PCB pad, then please don't let any traces and VIAs pass through this area.

**(Top view)**

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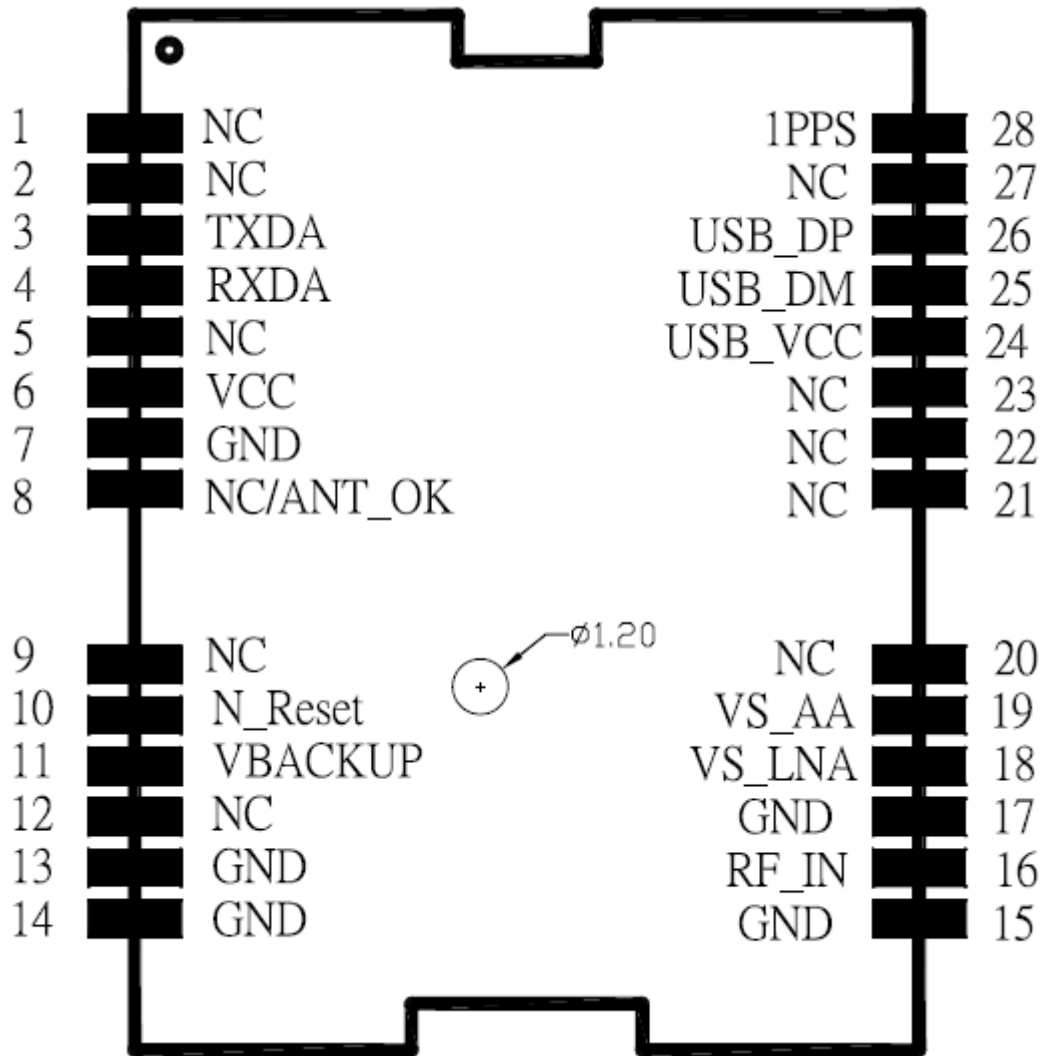
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## 2.3 Pin Configuration



(Top view)

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## 2.4 Pin Assignment

Pin	Name	I/O	Description & Note
1	NC	-	
2	NC	-	
3	TXDA	O	Serial Data Output for NMEA output (TTL)
4	RXDA	I	Serial Data Input for Firmware update (TTL)
5	NC	-	
6	VCC	PI	Main DC power input
7	GND	P	Ground
8	NC/ANT_OK	O	Not Connector/ Antenna status indicator
9	NC	-	
10	N_Reset	I	Reset Input, Low Active
11	VBACKUP	PI	Backup power input for RTC & navigation data keep
12	NC	-	
13	GND	P	Ground
14	GND	P	Ground
15	GND	P	Ground
16	RF_IN	I	Antenna Signal Input
17	GND	P	Ground
18	VS_LNA	PO	Output Voltage for Active Antenna
19	VS_AA	I	Active Antenna Voltage & Active Antenna detect
20	NC	-	
21	NC	-	
22	NC	-	
23	NC	-	
24	USB_VCC	PI	USB DC power input
25	USB_DM	I/O	USB port D-
26	USB_DP	I/O	USB port D+
27	NC	-	
28	1PPS	O	1PPS Time Mark Output 2.8V CMOS Level

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## 2.5 Description of I/O Pin

### NC, Pin1, Pin2

These are NC pins, they are not connected.

### TXDA, Pin3

This is the UART transmitter of the module. It outputs GPS information for application.

### RXDA, Pin4

This is the UART receiver of the module. It is used to receive commands from system.

### NC, Pin5

This pin is NC pin, it is not connected.

### VCC, Pin6

The main DC power supply for the module. The voltage should be kept between from 3V to 3.6V. The ripple must be limited under 50mVpp (Typical: 3.3V).

### GND, Pin7

Ground

### NC/ANT\_OK, Pin8

The pin is used for antenna type detection (passive or active) as a part of the antenna advisor system. If not used, keep open.

ANT\_OK function: The pin will output low or high voltage level to help differentiate the type of antenna connected at Pin16 (RF-In), providing that the proper Antenna Advisor circuit is used.

- If it outputs at low level, then Pin 16 is connected to passive antenna or is open circuit (bias<3mA).
- If it outputs at high level, then Pin 16 is connected to active antenna (3mA<bias<30mA) or is short to ground (bias>30mA).

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(To distinguish active or short status, please see Pin18 description)

## NC, Pin9

This pin is NC pin, it is not connected.

## N\_Reset, Pin10

Low active, it causes the module to reset. If not used, keep floating.

## VBACKUP, Pin11

This connects to the backup power of the GPS module. Power source (such as battery) connected to this pin will help the GPS chipset in keeping its internal RTC running when the main power source is removed. The voltage should be kept between 2.0V~4.3V, Typical 3.0V.

**IF VBACKUP power was not reserved, the GPS module will perform a lengthy cold start every time it is powered-on because previous satellite information is not retained and needs to be re-transmitted.**

If not used, keep open or ground.

## NC, Pin12

This pin is NC pin, it is not connected.

## GND, Pin13, Pin14, Pin 15

Ground

## RF\_IN, Pin16

This is the GPS RF signal input pin, which can be connected to a passive antenna or an active antenna.

When using a passive antenna, please connect the antenna directly to this pin.

When using an active antenna, it is typical for the RF\_IN pin to supply the necessary voltage to power the active antenna by routing power from Pin 19 VS\_AA. Please see **Pin 19 VS\_AA** and **Chapter 4** for more information on implementing active antenna.

- The active antenna current will be limited to < 30mA, for information on recommended active antenna specification, please refer to **Chapter 2.10**.

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## GND, Pin17

Ground

## VS\_LNA, Pin18 (for active antenna use only)

This pin provides the internal DC power source output for active antenna.

To enable Antenna Advisor, it is necessary to connect this pin to Pin 19 VS\_AA with an additional 10ohm resistor.

Leave VS\_LNA open if a passive antenna or an external antenna DC power source is used.

## VS\_AA, Pin19 (for active antenna use only)

This pin takes in DC power source and route it to RF\_IN to power the active antenna. It is also used as the active antenna detection of the module.

When using an active antenna, please connect this pin to an external DC power source (Range 3.0V to 3.6V, 3mA < current < 30mA), or add a 10 ohm resistor between Pin18 VS\_LNA and Pin19 VS\_AA to power it internally.

If the RF circuit is closed (as indicated by Pin 8), the output level of this pin is an indication on the status of antenna connected to Pin 16 RF\_IN as active (3mA < bias < 30mA) or short (bias > 30mA). See **Chapter 2.8: Antenna Status** for more details on the output level and their corresponding definition.

To enable Antenna Advisor, it is necessary to connect this pin to Pin 18 VS\_LNA with an additional 10ohm resistor.

Leave VS\_AA open if a passive antenna is used.

## NC, Pin20, 21, 22, 23

These are NC pins, they are not connected.

## USB\_VCC, Pin24

This pin is connected to an external DC power source that enables the USB interface of the module. The voltage should be kept between 3V to 3.6V. The ripple must be controlled under 50mVpp.

If not used, keep open or ground.

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## **USB\_DM, Pin25**

USB Port D- signal (USB\_VCC supplied), if not used, keep open.

## **USB\_DP, Pin26**

USB Port D+ signal (if USB\_VCC supplied), if not used, keep open.

## **NC, Pin27**

This pin is NC pin, it is not connected.

## **1PPS, Pin28**

This pin provides one pulse-per-second output from the module and synchronizes to GPS time.

Keep floating if not used. Default duration is 100ms.



## 2.6 Specification List

	Description
<b>GPS Solution</b>	MTK MT3329
<b>Frequency</b>	L1, 1575.42MHz
<b>Sensitivity<sup>1</sup></b>	Acquisition -148dBm, cold start Reacquisition -160dBm Tracking -165dBm
<b>Channel</b>	66 channels
<b>TTFF<sup>1</sup></b>	Hot start: 1 second typical Warm start: 33 seconds typical Cold start: 35 seconds typical
<b>Position Accuracy</b>	Without aid: 3.0m 2D-RMS DGPS(RTM,SBAS(WAAS,EGNOS,MSAS)): 2.5m 2D-RMS
<b>Velocity Accuracy</b>	Without aid : 0.1m/s DGPS(RTM,SBAS(WAAS,EGNOS,MSAS,GAGAN)):0.05m/s Without aid:0.1 m/s <sup>2</sup>
<b>Acceleration Accuracy</b>	Without aid:0.1 m/s <sup>2</sup> DGPS(RTM,SBAS(WAAS,EGNOS,MSAS)):0.05m/s <sup>2</sup>
<b>Timing Accuracy (1PPS Output)</b>	100 ns RMS
<b>Altitude</b>	Maximum 18,000m (60,000 feet)
<b>Velocity</b>	Maximum 515m/s (1000 knots)
<b>Acceleration</b>	Maximum 4G
<b>Update Rate</b>	1Hz (default), maximum 10Hz
<b>Baud Rate</b>	9600 bps (default)
<b>DGPS</b>	SBAS (defult) [WAAS, EGNOS, MSAS,GAGAN]
<b>AGPS</b>	Support
<b>Power Supply</b>	VCC: 3V to 3.6V / VBACKUP: 2.0V to 4.3V
<b>Current Consumption</b>	30mA acquisition, 24mA tracking
<b>Working Temperature</b>	-40 °C to +85 °C
<b>Vibration Condition Tested</b>	Frequency range: 10Hz~55Hz Magnitude: 0~7G Test period: 1 min/cycle, 120 cycles, 3 axis (X,Y,Z )
<b>Dimension</b>	22.4 x 17 x 2.2 mm, SMD
<b>Weight</b>	2g

<sup>1</sup> Reference to GPS chipset specification

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## 2.7 Absolute Maximum Ratings

The voltage applied for VCC should not exceed 6VDC.

	Symbol	Min.	Typ.	Max.	Unit
<b>Power Supply Voltage</b>	VCC	3.0	3.3	3.6	V
<b>Backup battery Voltage</b>	VBACKUP	2.0	3.0	4.3	V
<b>USB Supply Voltage</b>	USB_VCC	3.0	3.3	3.6	V

## 2.8 Operating Conditions

	Condition	Min.	Typ.	Max.	Unit
<b>Operation supply Ripple Voltage</b>	—	—	—	50	mVpp
<b>RX0 TTL H Level</b>	VCC=3.3V	2.0	—	VCC	V
<b>RX0 TTL L Level</b>	VCC=3.3V	0	—	0.8	V
<b>TX0 TTL H Level</b>	VCC=3.3V	2.4	—	2.8	V
<b>TX0 TTL L Level</b>	VCC=3.3V	0	—	0.4	V
<b>USB D+</b>	Standard	—	—	—	V
<b>USB D-</b>	Standard	—	—	—	V
<b>Current Consumption @ 3.3V</b>	Acquisition		30		mA
	Tracking		24		mA
<b>Backup Power Consumption@ 3V</b>	25°C		10		uA

## 2.9 Antenna Status (Antenna Advisor)

Pin 8 (ANT\_OK) and Pin 19 (VS\_AA) are hardware indicators on Antenna Status. Their output states and corresponding definition are described in the table below.

Pin	Active Antenna Connected (bias<30mA)	Active Antenna Short (bias>30mA)	Active Antenna Open or Passive Antenna Connected (bias<3mA)
Pin 8 (ANT_OK)	High Level	High Level	Low Level
Pin 19 (VS_AA)	High Level	Low Level	Not Applicable

Please also see Chapter 3.2 for software readout for antenna status on UART.

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## 2.10 GPS External Antenna Specification (Recommended)

It is important that the antenna gets a clear view of the sky and is positioned on a surface level to the horizon for best results. The following specification has to meet for the use reference design.

Characteristic	Specification
Polarization	Right-hand circular polarized
Frequency Received	1.57542GHz +/- 1.023MHz
Power Supply	3V to 3.6V
DC Current	3mA < IDC < 30mA at 3.3V
Total Gain	+ 15dBi
Output VSWR	< 2.5
Impedance	50ohm
Noise Figure	< 1.5dB

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## 3. Protocols

### 3.1 NMEA Output Sentences

**Table-1** lists each of the NMEA output sentences specifically developed and defined by MTK for use within MTK products

Table-1: NMEA Output Sentence	
Option	Description
GGA	Time, position and fix type data.
GSA	GPS receiver operating mode, active satellites used in the position solution and DOP values.
GSV	The number of GPS satellites in view satellite ID numbers, elevation, azimuth, and SNR values.
RMC	Time, date, position, course and speed data. Recommended Minimum Navigation Information.
VTG	Course and speed information relative to the ground.
GLL	Geographic Position, Latitude/Longitude

**Table-2** lists each of the custom NMEA output sentences specifically developed and defined by MTK for use within MTK products

Table-2: Custom NMEA Output Sentence	
Option	Description
PGACK	The status of antenna.



### GGA—Global Positioning System Fixed Data. Time, Position and fix related data

Table-3 contains the values for the following example :

\$GPGGA,064951.000,2307.1256,N,12016.4438,E,1,8,0.95,39.9,M,17.8,M,,\*65

Table-3: GGA Data Format			
Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Time	064951.00		hhmmss.ss
Latitude	2307.12562		ddmm.mmmmm
N/S Indicator	N		N=north or S=south
Longitude	12016.44382		dddmm.mmmmm
E/W Indicator	E		E=east or W=west
Position Fix Indicator	1		See Table-4
Satellites Used	8		Range 0 to 14
HDOP	0.95		Horizontal Dilution of Precision
MSL Altitude	39.9	meters	Antenna Altitude above/below mean-sea-level
Units	M	meters	Units of antenna altitude
Geoidal Separation	17.8	meters	
Units	M	meters	Units of geoid separation
Age of Diff. Corr.		second	Null
Checksum	*65		
<CR> <LF>			End of message termination

Table-4 Position Fix indicator

Table-4: Position Fix Indicator	
Value	Description
0	Fix not available
1	GPS fix
2	Differential GPS fix

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## GSA—GNSS DOP and Active Satellites

Table-5 contains the values for the following example :

\$GPGSA,A,3,29,21,26,15,18,09,06,10,,,,,2.32,0.95,2.11\*00

Table-5: GSA Data Format			
Name	Example	Units	Description
Message ID	\$GPGSA		GSA protocol header
Mode 1	A		See <b>Table-6</b>
Mode 2	3		See <b>Table-7</b>
Satellite Used	29		SV on Channel 1
Satellite Used	21		SV on Channel 2
....	....	....	....
Satellite Used			SV on Channel 12
PDOP	2.32		Position Dilution of Precision
HDOP	0.95		Horizontal Dilution of Precision
VDOP	2.11		Vertical Dilution of Precision
Checksum	*00		
<CR> <LF>			End of message termination

Table-6: Mode 1	
Value	Description
M	Manual—forced to operate in 2D or 3D mode
A	2D Automatic—allowed to automatically switch 2D/3D

Table-7: Mode 2	
Value	Description
1	Fix not available
2	2D (< 4 SVs used)
3	3D ( $\geq 4$ SVs used)

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## GSV—GNSS Satellites in View

Table-8 contains the values for the following example :

\$GPGSV,3,1,09,29,36,029,42,21,46,314,43,26,44,020,43,15,21,321,39\*7D

\$GPGSV,3,2,09,18,26,314,40,09,57,170,44,06,20,229,37,10,26,084,37\*77

\$GPGSV,3,3,09,07,,,26\*73

Table-8: GSV Data Format

Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Number of Messages	3		Range 1 to 3 <i>(Depending on the number of satellites tracked, multiple messages of GSV data may be required.)</i>
Message Number1	1		Range 1 to 3
Satellites in View	09		
Satellite ID	29		Channel 1 (Range 1 to 32)
Elevation	36	degrees	Channel 1 (Maximum 90)
Azimuth	029	degrees	Channel 1 (True, Range 0 to 359)
SNR (C/No)	42	dBHz	Range 0 to 99, (null when not tracking)
....	....	....	....
Satellite ID	15		Channel 4 (Range 1 to 32)
Elevation	21	degrees	Channel 4 (Maximum 90)
Azimuth	321	degrees	Channel 4 (True, Range 0 to 359)
SNR (C/No)	39	dBHz	Range 0 to 99, (null when not tracking)
Checksum	*7D		
<CR> <LF>			End of message termination

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## RMC—Recommended Minimum Navigation Information

Table-9 contains the values for the following example :

\$GPRMC,064951.000,A,2307.1256,N,12016.4438,E,0.03,165.48,260406, 3.05,W,A\*55

Table-9: RMC Data Format			
Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTC Time	064951.00		hhmmss.ss
Status	A		A=data valid or V=data not valid
Latitude	2307.12562		ddmm.mmmmm
N/S Indicator	N		N=north or S=south
Longitude	12016.44382		dddmm.mmmmm
E/W Indicator	E		E=east or W=west
Speed over Ground	0.034	knots	
Course over Ground			Null
Date	260406		ddmmyy
Magnetic Variation	3.05,W	degrees	E=east or W=west <b>(Need AscenKorea Customization Service)</b>
Mode	A		A= Autonomous mode D= Differential mode E= Estimated mode
Checksum	*55		
<CR> <LF>			End of message termination

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## VTG—Course and speed information relative to the ground

Table-10 contains the values for the following example:

\$GPVTG,165.48,T,,M,0.03,N,0.06,K,A\*37

Table-10: VTG Data Format			
Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
Course			Null
Reference	T		True
Course		degrees	Measured heading
Reference	M		Magnetic <i>(Need AscenKorea Customization Service)</i>
Speed	0.034	knots	Measured horizontal speed
Units	N		Knots
Speed	0.06	km/hr	Measured horizontal speed
Units	K		Kilometers per hour
Mode	A		A= Autonomous mode D= Differential mode E= Estimated mode
Checksum	*06		
<CR> <LF>			End of message termination

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## GLL—Geographic Position, Latitude/Longitude

Table-11 contains the values for the following example:

\$GPGLL,2305.91626,N,12017.06438,E,051817.00,A,A\*61

Table-11: VTG Data Format			
Name	Example	Units	Description
Message ID	\$GPGLL		GLL protocol header
Latitude	2305.91626		ddmm.mmmmm
N/S Indicator	N		N=north or S=south
Longitude	12017.06438		dddmm.mmmmm
E/W Indicator	E		E=east or W=west
UTC Time	064951.00		hhmmss.ss
Status	A		A=data valid or V=data not valid
Mode	A		A= Autonomous mode D= Differential mode E= Estimated mode
Checksum	*61		
<CR> <LF>			End of message termination

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## 3.2 Antenna Status Protocol (Antenna Advisor)

The function is for active antenna only and requires proper Antenna Advisor circuit to be implemented. (See Chapter 4.2 for more detail)

### PGACK—Status of antenna

Table-12 contains the values for the following example:

\$PGACK,13,3 \*6F

Table-12: PGACK Data Format			
Name	Example	Units	Description
Message ID	\$PGACK		PGACK protocol header
Command ID	13		The id of command
Reference	3		Value of antenna status

### Example:

\$PGACK,13,value\*checksum

Value: 1=>Active Antenna Short

2=>Passive Antenna Connected or Active Antenna Open

3=>External antenna active

## 3.3 MTK NMEA Command Protocols

The complete MTK NMEA Command list document is available by request. Contact AscenKorea for more details.

### Packet Type:

103 PMTK\_CMD\_COLD\_START

### Packet Meaning:

Cold Start : Don't use Time, Position, Almanacs and Ephemeris data at re-start.

### Example:

\$PMTK103\*30<CR><LF>

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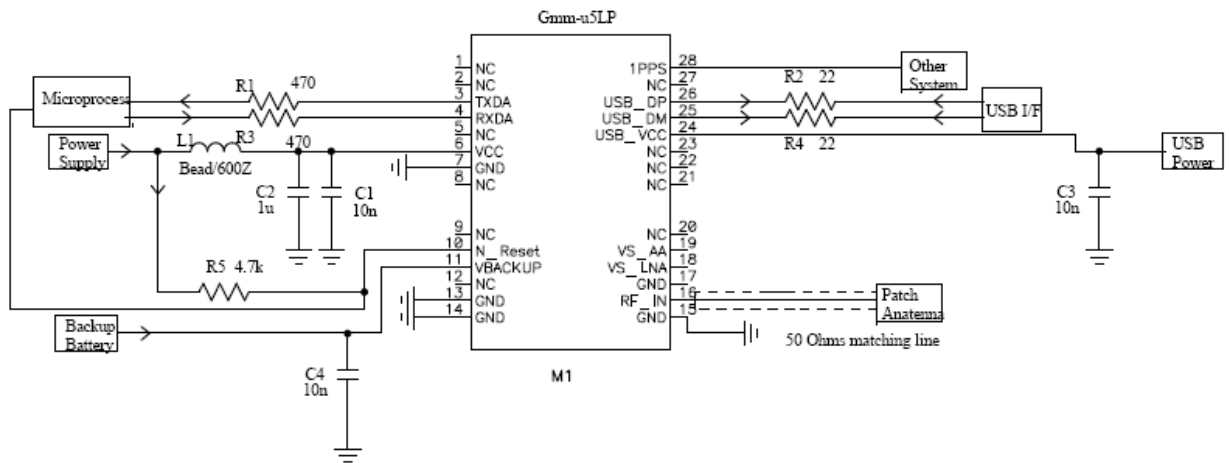


## 4. Reference Design

This chapter introduces the reference schematic design for the best performance. Additional tips and cautions on design are well documented on Application Note, which is available upon request.

### 4.1 Patch (Passive) Antenna

When using a passive antenna, please connect the antenna directly to Pin16, RF\_IN.



Note:

1. Ferrite bead L1 is added for power noise reduction.
2. Ferrite bead L1 is added for power noise reduction.  
For C2, the value chosen depends on the amount of system noise, the range from 1uF to 100uF is reasonable.
3. Damping resistors R1, R2, R3, R4 and R5 could be modified based on system application.

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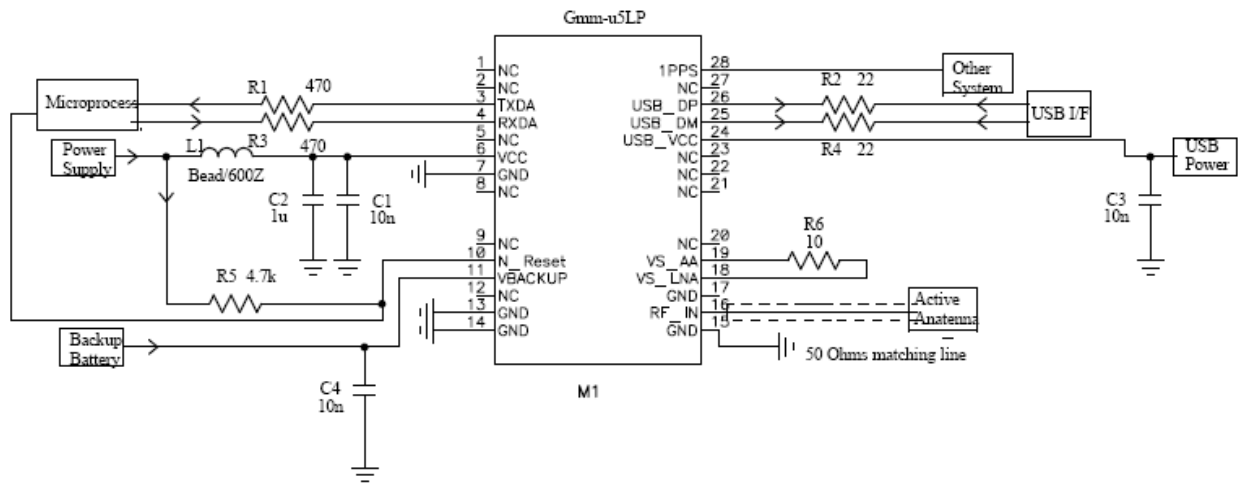
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## 4.2 Active Antenna with Antenna Advisor

When using an active antenna, a supply voltage is typically required to drive the internal LNA located inside the active antenna. For majority of the active antenna, the power will be sent on the same coaxial cable used for GPS signal reception through the RF\_IN Pin (Pin 16). For Gmm-u5LP, this power source is inputted from Pin 19 VS\_AA, which is designed to route the power to RF\_IN Pin.

To power the active antenna through module's own power supply, please add an additional 10 ohm resistor between Pin18 VS\_LNA and Pin19 VS\_AA, which also enables the Antenna Advisor function such as open and short circuit detection and protection.



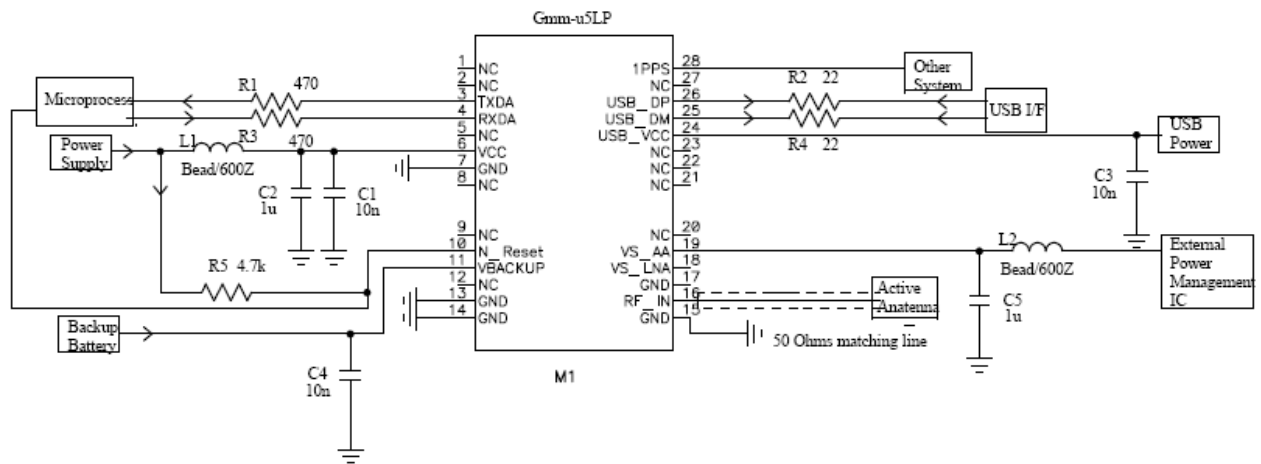
**Note:**

1. Ferrite bead L1 is added for power noise reduction.
2. C1, C2, C3, and C4, decoupling capacitor should be put near the module.  
For C2, the value chosen depends on the amount of system noise, the range from 1uF to 100uF is reasonable.
3. Damping resistors R1, R2, R3, R4, and R5 could be modified based on system application.
4. An additional resistor R6 (10ohm) is used to connect Pin 19 VS\_LNA with Pin 18 VS\_AA, which also enables "Antenna Advisor" mechanism.

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## 4.3 Active Antenna with External Power Management IC

The reference design is for those who want to use a power management IC to perform external antenna status detection by defining their own behavior. The power IC should supply power to Pin 19 VS\_AA (Range 3.0V to 3.6V, 3mA < current < 30mA), which will be routed to Pin 16 RF\_IN internally, and this in turn will supply the power to the active antenna. (There is an internal inductor between VS\_AA and RF\_IN).



**Note:**

1. Ferrite bead L1 and L2 are added for power noise reduction.
2. C1, C2, C3 and C4 decoupling capacitor should be put near the module.  
For C2 and C5 the value chosen depends on the amount of system noise, the range from 1uF to 100uF is reasonable.
3. Damping resistors R1, R2, R3, R4 and R5 could be modified based on system application.
4. "Antenna Advisor" mechanism will be not operational when using this design

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## 5. Packing and Handling

GPS modules, like any other SMD devices, are sensitive to moisture, electrostatic discharge, and temperature. By following the standards outlined in this document for AscenKorea GPS module storage and handling, it is possible to reduce the chances of them being damaged during production set-up. This document will go through the basics on how AscenKorea packages its modules to ensure they arrive at their destination without any damages and deterioration to performance quality, as well as some cautionary notes before going through the surface mount process.

**⚠ Please read the sections II to V carefully to avoid damages permanent damages due to moisture intake**

**⚠ GPS receiver modules contain highly sensitive electronic circuits and are electronic sensitive devices and improper handling without ESD protections may lead to permanent damages to the modules. Please read section VI for more details.**

### 5.1 Moisture Sensitivity

AscenKorea GPS modules are moisture sensitive, and must be pre-baked before going through the solder reflow process. It is important to know that:

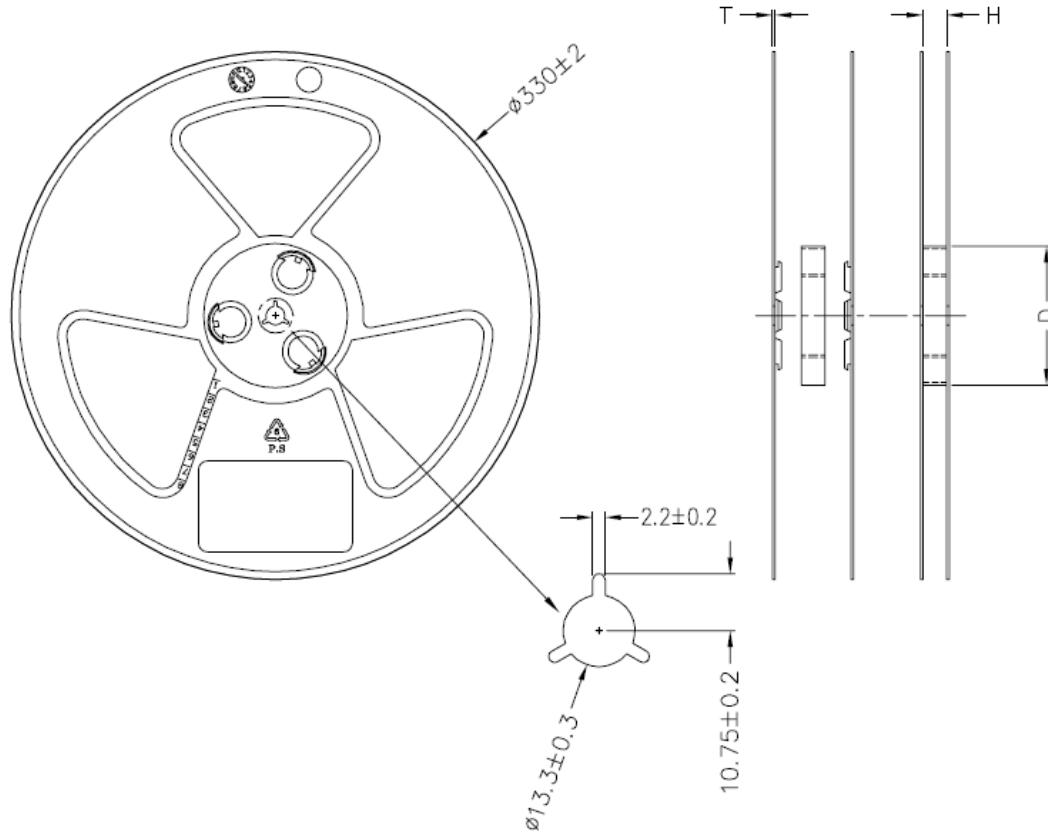
**AscenKorea GPS modules must complete solder reflow process in 72 hours after pre-baking.**

This maximum time is otherwise known as “Floor Life”

If the waiting time has exceeded 72 hours, it is possible for the module to suffer damages during the solder reflow process such as cracks and delamination of the SMD pads due to excess moisture pressure.

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## 5.2 Tape Reel Packing Information 1Kpcs/Reel

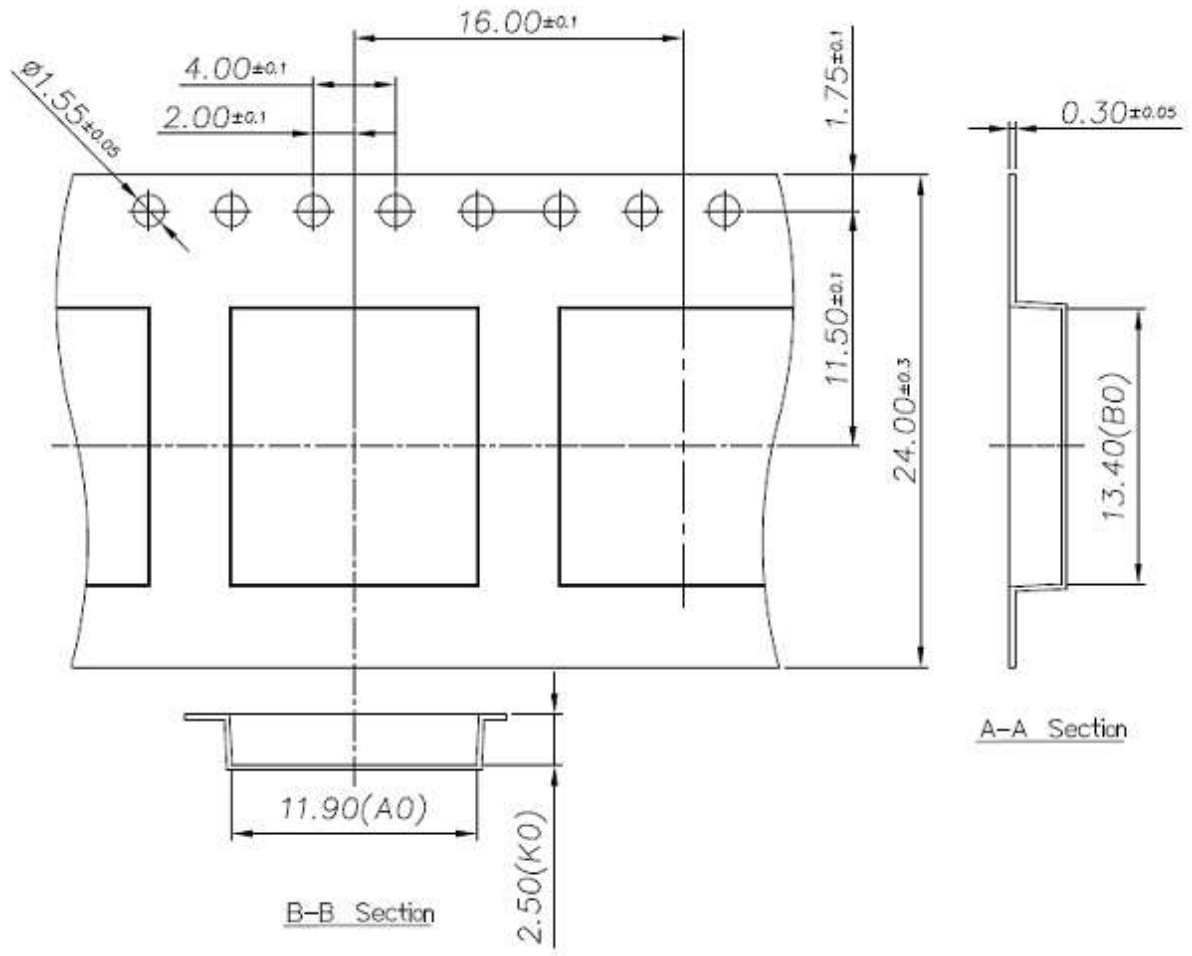


Spec: H:  $24.5 \pm 1.5$ , T:  $2.2 \pm 0.2$ , D:  $99 \pm 1.5$

Note: 13" Reel, Material : P.S

Unit: (mm)

Figure 1: Reel Dimension



A0	$11.9 \pm 0.10$
B0	$13.4 \pm 0.10$
K0	$2.5 \pm 0.10$

Unit: (mm)

Figure 2: Tape Dimension

The moisture color coded card provides an insight to the relative humidity percentage (RH). When the GPS modules are taken out, it should be around or lower than 30% RH level.

Outside each electrostatic bag is a caution label for moisture sensitive device.

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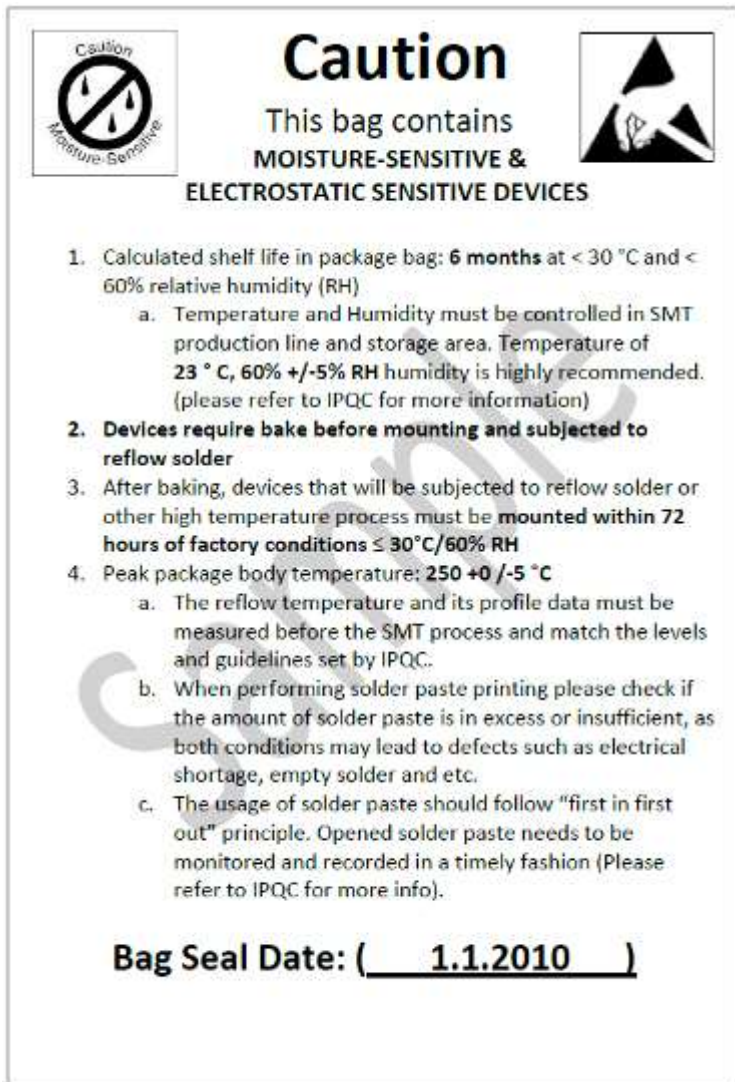


Figure 3: Example of moisture color coded card and caution label



## 5.3 Storage and Floor Life Guideline

Since AscenKorea modules must undergo solder-reflow process in 72 hours after it has gone through pre-baking procedure, therefore if it is not used by then, it is recommended to store the GPS modules in dry places such as dry cabinet.

The approximate shelf life for AscenKorea GPS modules packages is 6 months from the bag seal date, when store in a non-condensing storage environment (<30°C/60% RH)

**⚠ It is important to note that it is a required process for AscenKorea GPS modules to undergo pre-baking procedures, regardless of the storage condition.**

## 5.4 Drying

Because the vapor pressures of moisture inside the GPS modules increase greatly when it is exposed to high temperature of solder reflow, in order to prevent internal delaminating, cracking of the devices, or the “popcorn” phenomenon, it is a **necessary requirement** for AscenKorea GPS module to undergo pre-baking procedure before any high temperature or solder reflow process.

The recommendation baking time for AscenKorea GPS module is as follows:

- ✓ **60°C for 8 to 12 hours**

Once baked, the module’s floor life will be “reset”, and has additional 72 hours in normal factory condition to undergo solder reflow process.

**⚠ Please limit the number of times the GPS modules undergoes baking processes as repeated baking process has an effect of reducing the wetting effectiveness of the SMD pad contacts. This applies to all SMT devices.**

**⚠ Oxidation Risk: Baking SMD packages may cause oxidation and/or intermetallic growth of the terminations, which if excessive can result in solderability problems during board assembly. The temperature and time for baking SMD packages are therefore limited by solderability considerations. The cumulative bake time at a temperature greater than 90°C and up to 125°C shall not exceed 96 hours. Bake temperatures higher than 125°C are now allowed.**

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## 5.5 ESD Handling



**Please carefully follow the following precautions to prevent severe damage to GPS modules.**

AscenKorea GPS modules are sensitive to electrostatic discharges, and thus are Electrostatic Sensitive Devices (ESD). Careful handling of the GPS modules and in particular to its patch antenna (if included) and RF\_IN pin, must follow the standard ESD safety practices:

- ✓ Unless there is a galvanic coupling between the local GND and the PCB GND, then the first point of contact when handling the PCB shall always be between the local GND and PCB GND.
- ✓ Before working with RF\_IN pin, please make sure the GND is connected
- ✓ When working with RF\_IN pin, do not contact any charges capacitors or materials that can easily develop or store charges such as patch antenna, coax cable, soldering iron.
- ✓ Please do not touch the mounted patch antenna to prevent electrostatic discharge from the RF input
- ✓ When soldering RF\_IN pin, please make sure to use an ESD safe soldering iron (tip).

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## 6. Reflow Soldering Temperature Profile

The following reflow temperature profile was evaluated by Ascenkorea and has been proven to be reliable qualitatively. Please contact us beforehand if you plan to solder this component using a deviated temperature profile as it may cause significant damage to our module and your device.

All the information in this sheet can only be used only for Pb-free manufacturing process.

### 6.1 SMT Reflow Soldering Temperature Profile (Reference Only)

Average ramp-up rate (25 ~ 150°C): 3°C/sec. max.

Average ramp-up rate (270°C to peak): 3°C/sec. max.

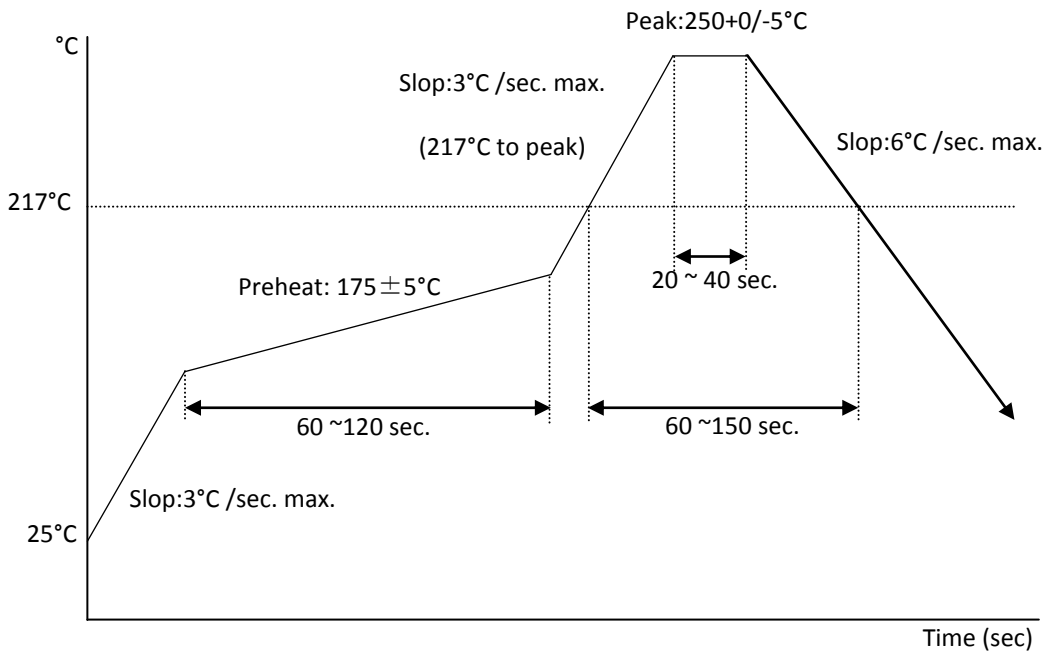
Preheat: 175 ± 25°C, 60 ~ 120 seconds

Temperature maintained above 217°C: 60~150 seconds

Peak temperature: 250 +0/-5°C, 20~40 seconds

Ramp-down rate: 6°C/sec. max.

Time 25°C to peak temperature: 8 minutes max.



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## 6.2 Cautions on Reflow Soldering Process

1. Module must be pre-baked **before** going through SMT solder reflow process.
2. The usage of solder paste should follow “first in first out” principle. Opened solder paste needs to be monitored and recorded in a timely fashion (can refer to IPQC for related documentation and examples).
3. Temperature and humidity must be controlled in SMT production line and storage area. Temperature of 23°C, 60±5% RH humidity is recommended. (please refer to IPQC for related documentation and examples)
4. When performing solder paste printing, please notice if the amount of solder paste is in excess or insufficient, as both conditions may lead to defects such as electrical shortage, empty solder and etc.
5. The reflow temperature and its profile data must be measured before the SMT process and match the levels and guidelines set by IPQC.

## 6.3 Manual Soldering

### Soldering iron:

Bit Temperature: Under 380°C      Time: Under 3 sec.

### Notes:

1. Please do not directly touch the soldering pads on the surface of the PCB board, in order to prevent further oxidation
2. The solder paste must be defrosted to room temperature before use so it can return to its optimal working temperature. The time required for this procedure is unique and dependent on the properties of the solder paste used.
3. The steel plate must be properly assessed before and after use, so its measurement stays strictly within the specification set by SOP.
4. Please watch out for the spacing between soldering joint, as excess solder may cause electrical shortage
5. Please exercise with caution and do not use extensive amount of flux due to possible siphon effects on neighboring components, which may lead to electrical shortage.

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6. Please do not use the heat gun for long periods of time when removing the shielding or inner components of the GPS module, as it is very likely to cause a shift to the inner components and will leads to electrical shortage.

## 7. Contact

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